			DEPARTMENT OF COMMERCE TENT AND TRADEMARK OFFICE		ATTY. DOCKET NO.		APPLICATION NO.			
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U.S. PATENT DOCUMENTS										
•EXAMINER INITIAL		DOCUMENT NUMBER	DATE		NAME	CLASS	SUBCLASS		DATE OPRIATE	
۶. ۲	AA	4,578,561	03/25/86	Corby, Jr. et al. 219 124.34		124.34				
m· m	AB	4,835,450	05/30/89	Suzuki		318	568.13			
~~~	AC	5,083,073	01/21/92	Kato		318	577			
m. m	AD	5,350,269	09/27/94	Azuma et al.		414	416			
m· ~	ΑE	5,454,775	10/03/95	Cullen et al.		483	16			
m· m	AF	6,341,246	01/22/02	Gerstenberger et al.		700	245			
m. m	AG	6,466,843	10/15/02	Bonanni e	et al.	700	245			
m. ~	AH	6,804,416	10/12/04	Bachelder	et al.	382	294			
me m	Al	2004/0114033	06/17/04	Eian et al.		348	42			
min	Ŋ	60/413,180		Eian et al.				09/23/02		
			FOREI	GN PATEN	T DOCUMENTS					
		DOCUMENT NUMBER	DATE	COUNTRY				TRANSLATION YES NO		
m. ~	AK	0151417	08/14/85	EP			, <u>.</u>			
m. m	AL	0493612	07/08/92	EP						
m. m	AM	0951968	10/27/99	EP						
m· m	AN	401124072	05/89	JP						
m	AO	0911603 B1	04/28/99	EP (with r	n machine translation)			X		
		ОТНЕ	R PRIOR A	RT (Including	Author, Title, Date, Pertinent Pa	ges, Etc.)				
	AP	Denzler, J., e	t al., "Learn	ing, Trackir	ng and Recognition of	3D Obj	ects," Procee	dings o	of the	
m·m			Internation	aLConfere	nce on Intelligent Rob	ots_and	Systems (No	date.		
	<del>,  </del>	available.)								
<b>.</b>	ÁQ	1	•		Real World," Proceed	-				
		Conference on Intelligent Robots and Systems (IROS), XP000512662, Vol. 1, Munich,								
September 12, 1994, pp. 89-96.  EXAMINER  DATE CONSIDERED										
McDreunel Mare 9-10-2005										
* EXAMINER: Initial if reference considered, whether or not criteria is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant(s).										

Sheet <u>2</u> of <u>2</u>

FORM PTO-1449 (REV.7-80)	)		U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE						PPLICATION NO. 0/634,874			
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m. ~	ВА	60/587,488	-	Boca et a	ca et al.			07/14	1/04			
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	ВР	W. Meyer, "C	W. Meyer, "One-Eyed Robots With 3D Vision," ISRA Vision Systems AG, Press News,									
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<u>~~~</u>	во		uidance with	n a Single (	Camera," ISRA Vision	Systems	AG. (No d	ate				
m , m			available.)									
	BR		3D Vision with One Camera,									
		_	URL=http://neu.isravision.com/likecms/index.php?site=site.html&dir=isra&nav=162.download date April 12, 2005.									
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